

# Maritime Integrated PNT System

Core element for safe ship navigation

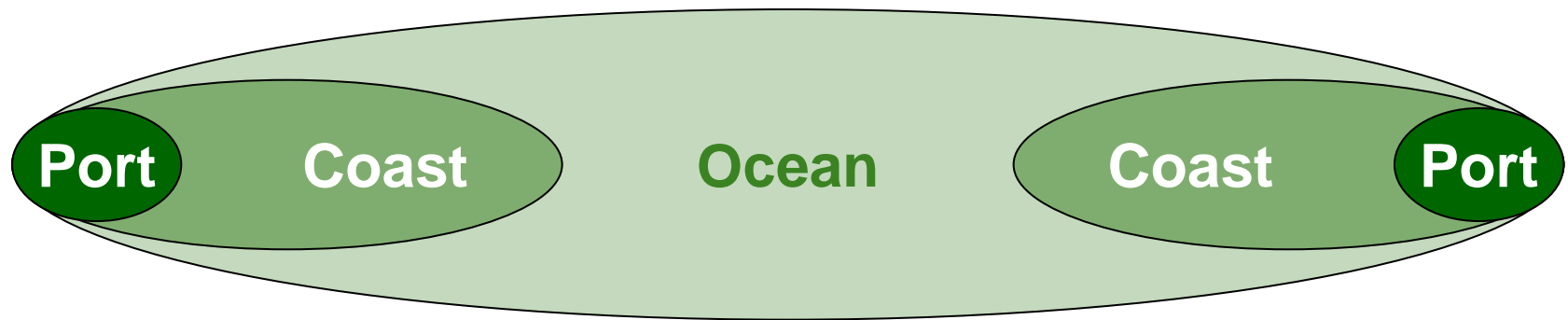
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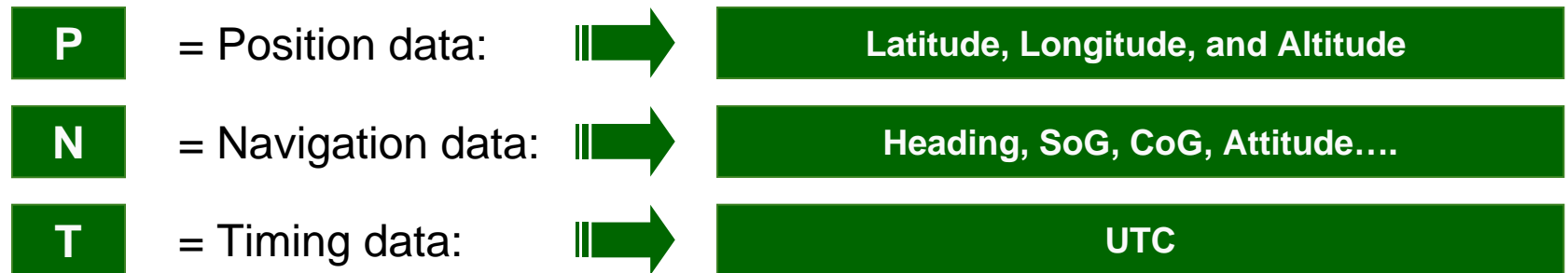
Deutsches Zentrum  
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# Maritime Integrated PNT System

= **overlay of satellite based, ashore and aboard components**, whose integrated use can ensure the accurate and reliable provision of PNT output data to applications during all phases of vessel navigation

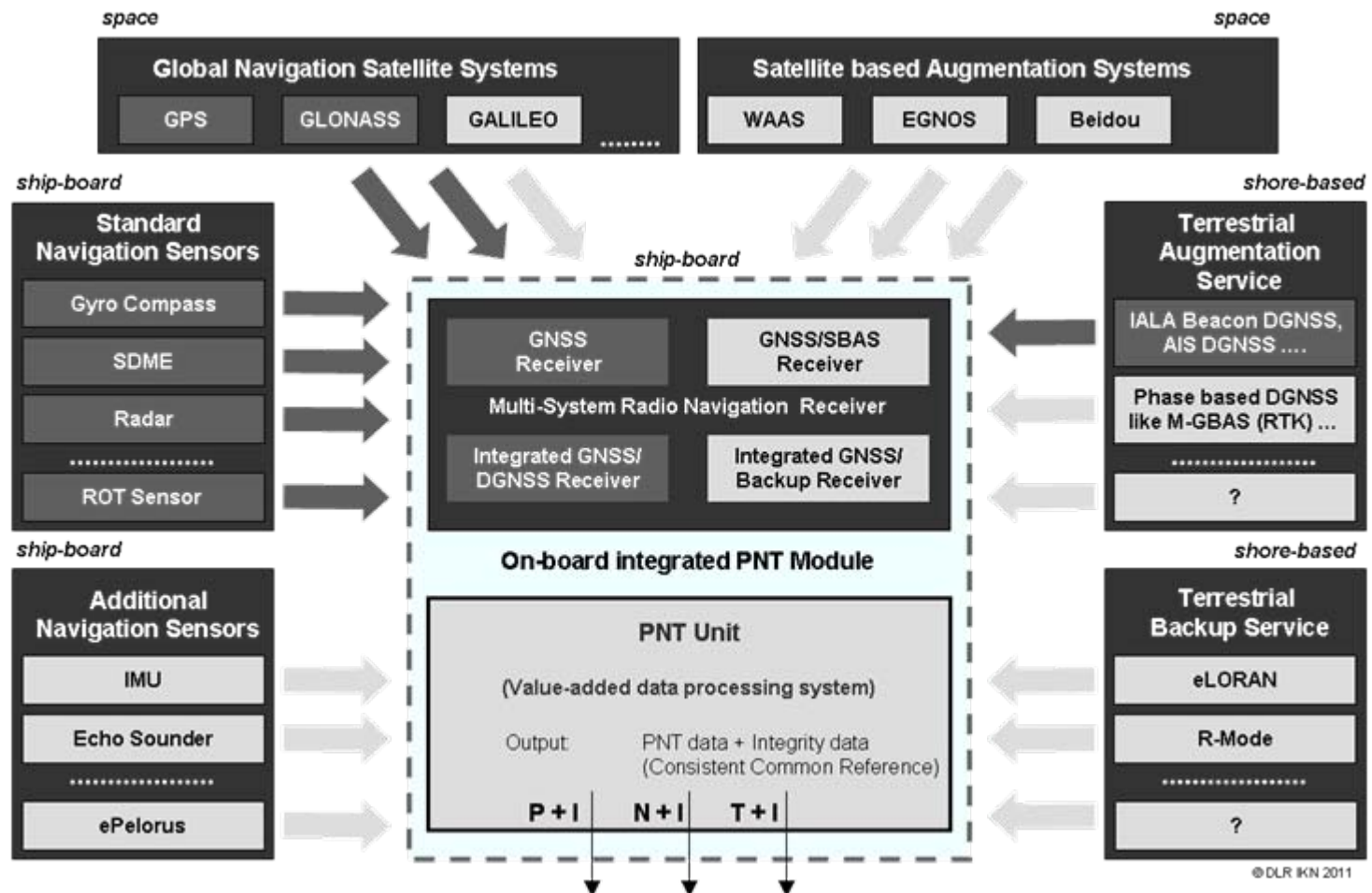


**Accurate provision** during changing accuracy requirements:



# Overview of PNT components

practice, existing, and future



# Accuracy Requirements on future GNSS

## IMO A.915(22): Minimum Requirements on future GNSS

	System Level Parameters				Service Level Parameters			
	Absolute Accuracy	Integrity			Availability (%) per 30 days	Continuity (%) over 3 hours	Coverage	Fix Interval <sup>2</sup> (s)
	Horizontal (m)	Alert Limit (m)	Time to Alarm <sup>2</sup> (s)	Integrity Risk (per 3h)				
Ocean	10	25	10	10 <sup>-5</sup>	99,8	N/A <sup>1</sup>	global	1
Coastal	10	25	10	10 <sup>-5</sup>	99,8	N/A <sup>1</sup>	global	1
Port approach and restricted waters	10	25	10	10 <sup>-5</sup>	99,8	99,97	regional	1
Port	1	2,5	10	10 <sup>-5</sup>	99,8	99,97	local	1
Automatic Docking	0,1	0,25	10	10 <sup>-5</sup>	99,8	99,97	local	1

1 - Continuity is not relevant for ocean and coastal areas

2 - More stringent requirements may be necessary for ships operating above 30 knots

## Accuracy and Integrity Requirements for all PNT data ?



# Identified User Needs

[IMO NAV56-WP.5 E-NAV report]

Examples

## Identification of Reliability

- Automatically assessment of accuracy and integrity of hydrographical data, position fixing data, radar data, and other navigation relevant data;
- Graphical indication of assessment results;

## Improvement of Reliability

- Reduction of failures and malfunction of electronic equipment
- Assessment and quantification of reliability

## Alert Management

- Coordination and weighting of bridge alerts
- Support of decision making without undue diversion

## Approaches

- Data and System Integrity
- Analysis
- Redundancy
- Backup
- Common Maritime Data / Information Structure
- Harmonised Meaning of Assessment Results
- .....



# Integrity

## Data Integrity

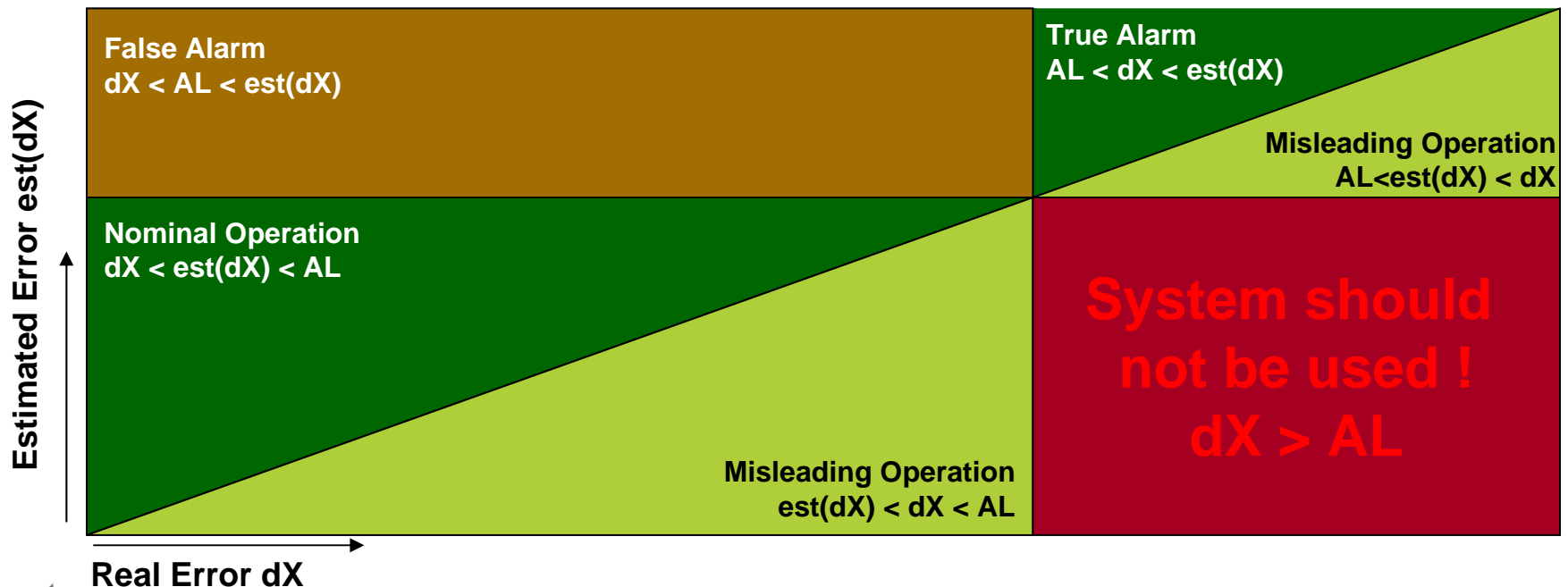
Desired data are provided completely, undisturbed and accurately.

$X = \text{"true"} \quad \text{or} \quad \text{"accurate"}$

## System Integrity

Fulfillment of specified functionalities and related requirements.

$State = F\{x_1, x_2 \dots x_N\} = \text{"reliable"}$





# Objective of Integrated PNT System

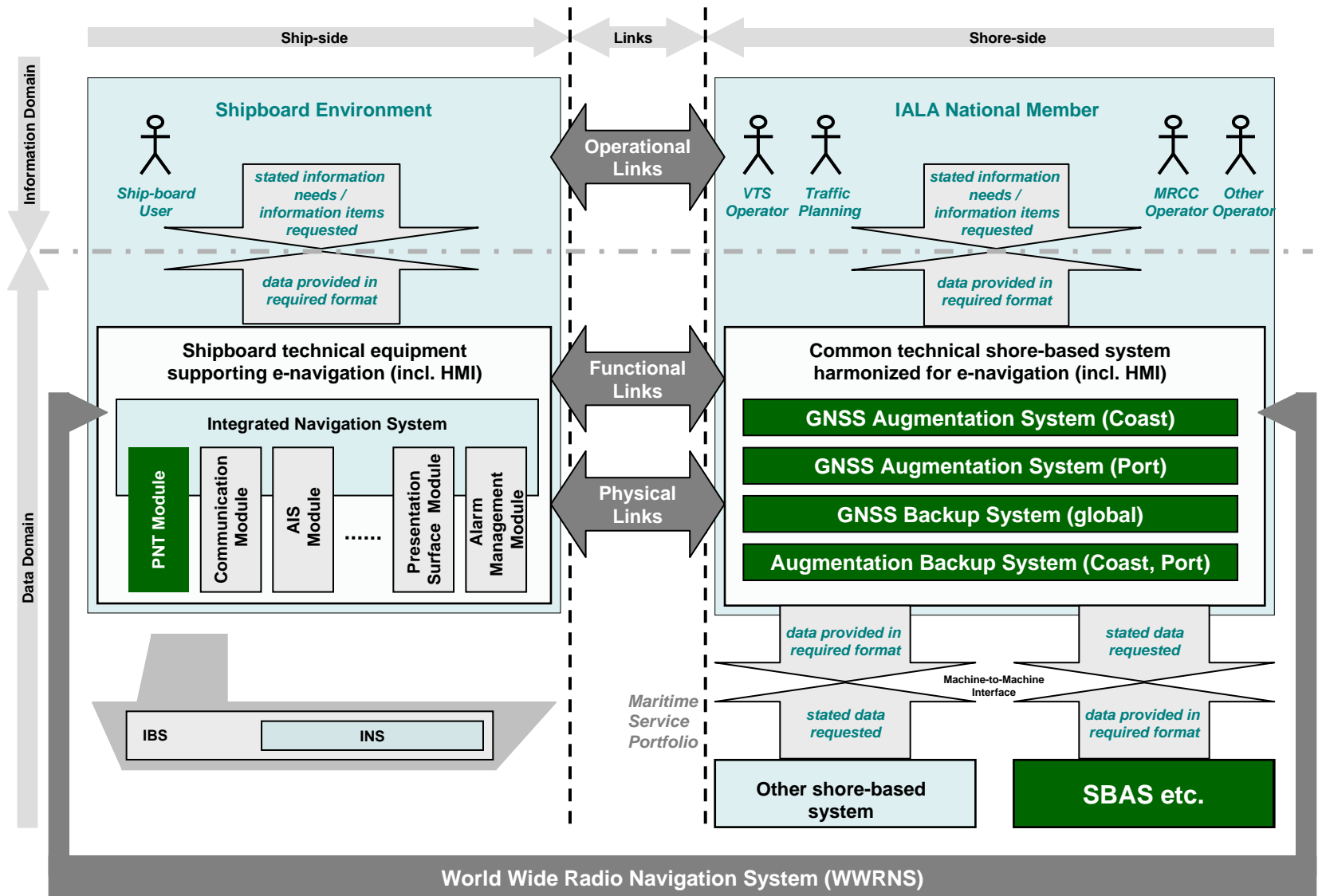
## Accurate and reliable provision of

<b>P</b>	= Position data:	➡	Latitude, Longitude, and Altitude
<b>N</b>	= Navigation data:	➡	Heading, SoG, CoG, Attitude....
<b>T</b>	= Timing data:	➡	UTC
<b>I</b>	= Integrity data:	➡	Accuracy assessment results of PNT data
<b>A</b>	= Alert data:	➡	PNT&I data vs. requirements (paradigm shift)

## requires

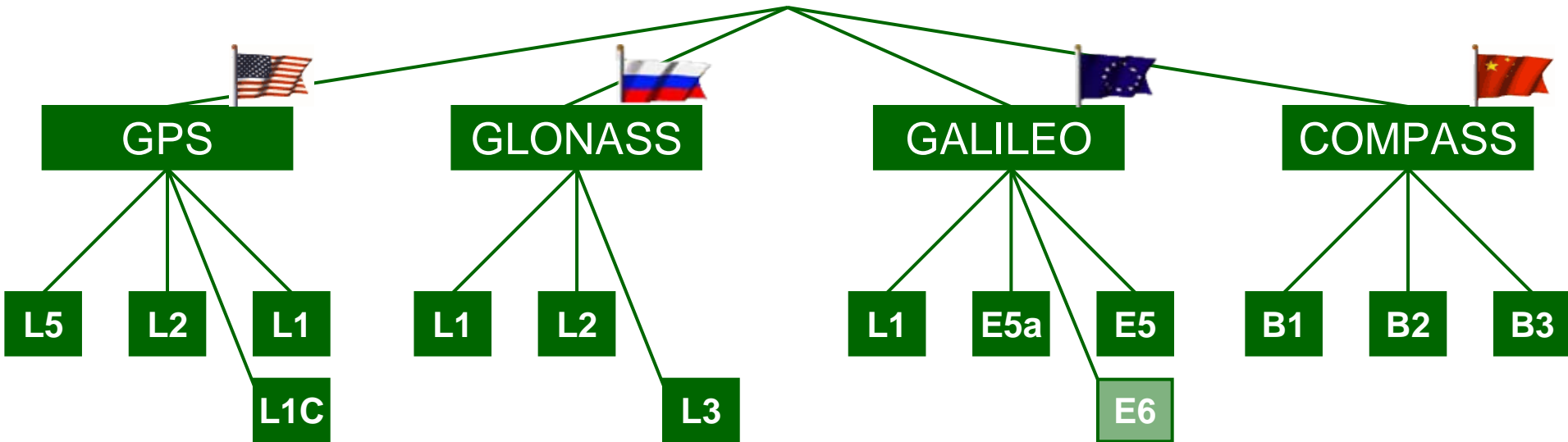
- basis set of ship-board sensors and ashore services to ensure **complete provision of PNT data with desired accuracy** (basis functionality)
- redundant layout (multi-system and multi-sensor approach) to increase the **reliability of PNT data provision** and to ensure the **accuracy assessment** (integrity functionality)

# E-Navigation Architecture & Integrated PNT System





# The future redundant GNSS



## Improved PT-data provision by:

- Alternative usable single-frequency GNSS services
- Use of dual- and triple-frequency GNSS service
- Increased total number of available satellite navigation signals : ➔ improved RAIM

## Modernisation of GNSS implicates:

- substitution of GNSS receiver equipment (new signals, multi-system positioning)
- harmonised utilisation concept of signals to provide the “best” PT&I-results.

# GNSS Augmentation Systems

## Aim

- Increase accuracy of GNSS based positioning by application of C-DGNSS
- Accuracy assessment (integrity) by monitoring of GNSS/DGNSS (LIM, FFIM)
- Provision of C-DGNSS related integrity information

## Practice

### IALA Beacon DGNSS (IALA R-121):

- Fulfilment of IMO coast requirements
- Provision of C-DGNSS corrections (PRC, RRC) and integrity information

## Completion

### AIS Base Station (IALA A-124):

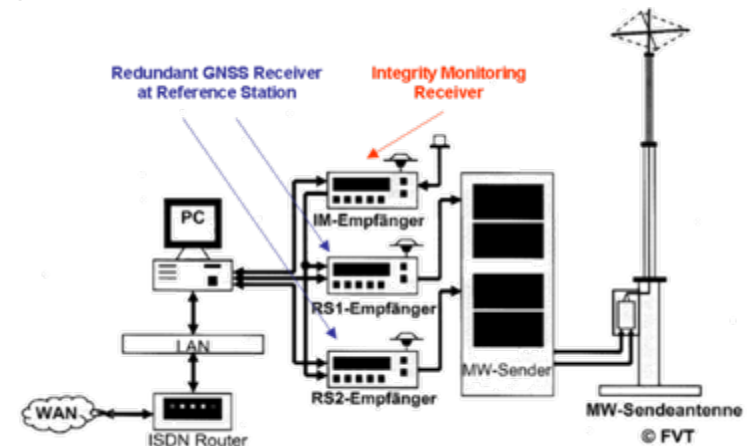
- Provision of C-DGNSS and integrity corrections via AIS VHF Data Link (Message 17)

### Modernisation of IALA Beacon DGNSS:

- Exchange and modernisation of GNSS receiver equipment
- Cost-efficient approaches for services (VRS concept)

### Augmentation for port navigation:

- P-DGNSS based approaches (Rotterdam, Hamburg, FoHa Rostock, ...)
- Standardisation is open task



Channel capacity!

# GNSS Backup Systems

## Aim

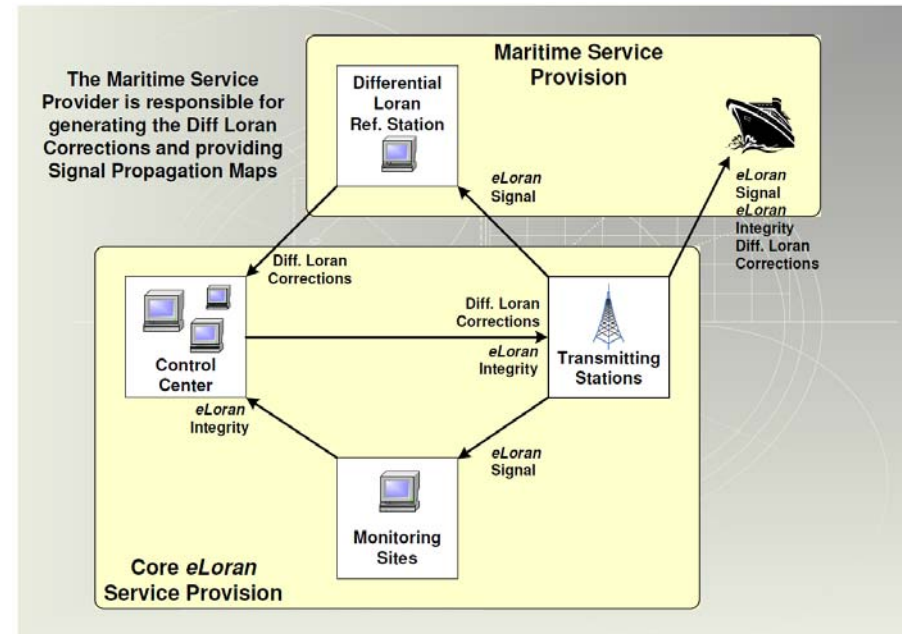
- Compensation of GNSS vulnerability (interferences, jamming, and ionosphere) by GNSS independent determination of PNT data

## Candidate 1

### eLoran

(Long-RANGE Navigation):

- based on ground wave signal propagation (100 KHz)
- additional data channel to provide
  - differential eLoran corrections to compensate ground wave propagation effects
  - warnings of anomalous radio propagation conditions
  - GNSS corrections
- enables work of eLoran compass:
  - requires H-field (Magnetic Loop Antenna) for direction finding
  - offers heading determination better than 1°



Accuracy	Availability	Integrity	Continuity
0.004 – 0.01 nautical mile (8 – 20 meters)	0.999 – 0.9999	0.999999 ( $1 \times 10^{-7}$ )	0.999 – 0.9999 over 150 seconds

Source: International eLoran Association, eLoran Definition Document (2007)

# GNSS Backup Systems

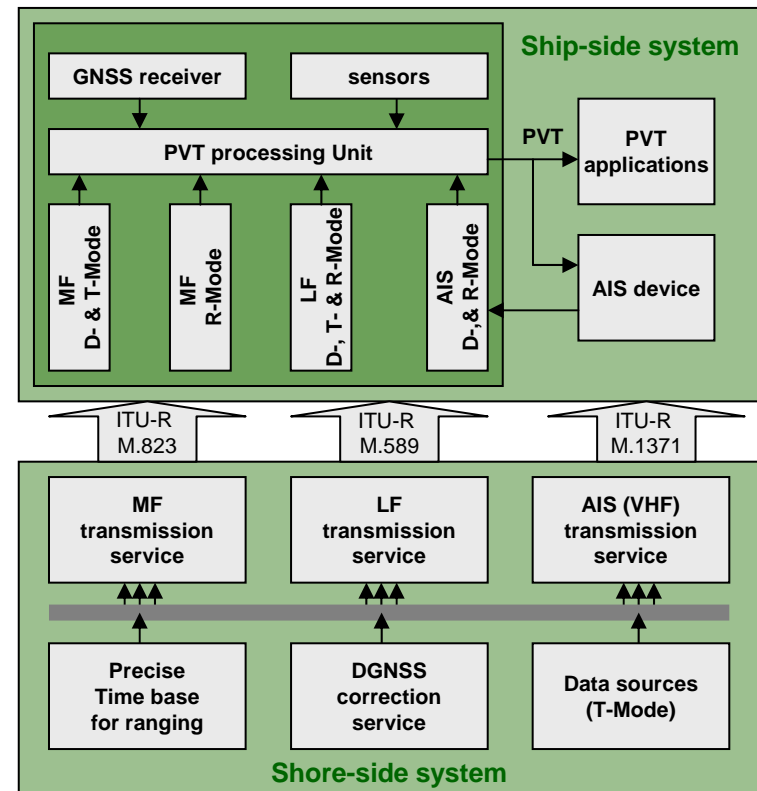
## Aim

- Compensation of GNSS vulnerability (interferences, jamming, and ionosphere) by GNSS independent determination of PNT data

## Candidate 2

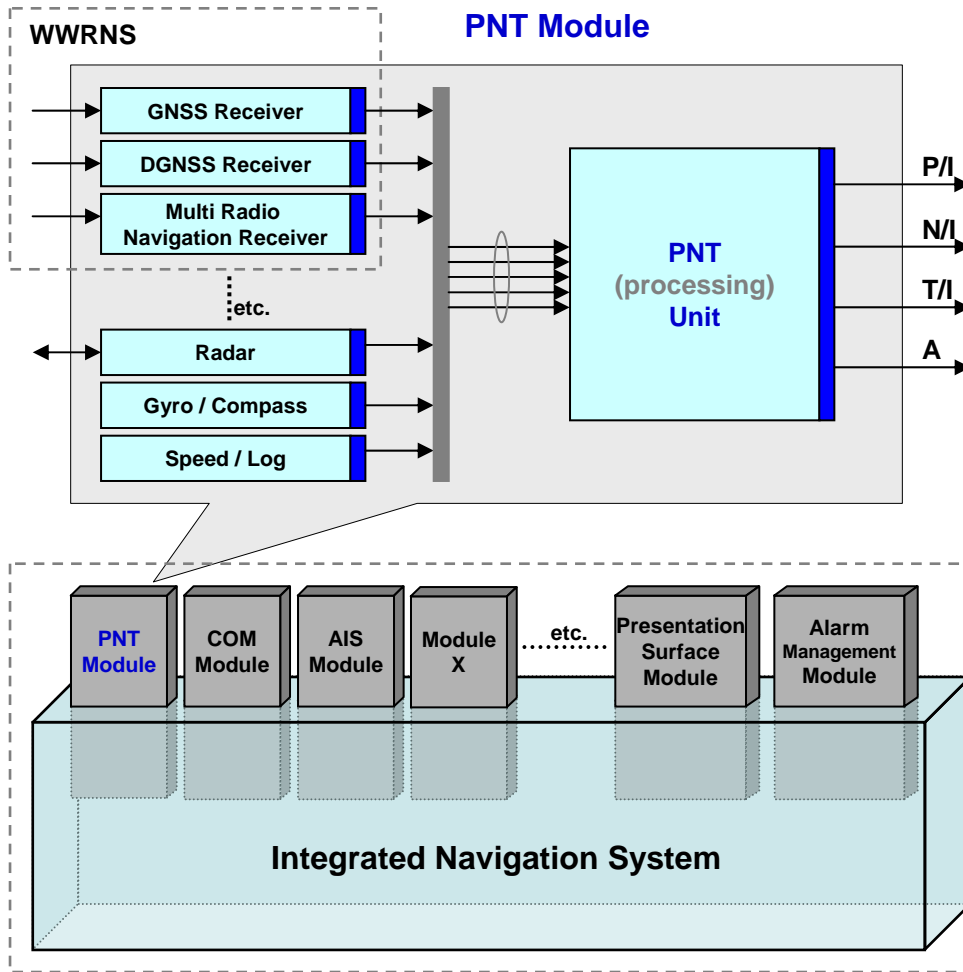
### R-Mode (Ranging Mode):

- based on existing IALA Beacon DGNSS and AIS service infrastructure (MF and VHF):
  - requires modification of transmitting station
  - and extension with GNSS independent timing source
- additional provision of timing information
  - to derive distance measurements
  - to enable GNSS independent position determination based on multi-station approach
- next steps
  - feasibility study
  - field tests



Visionary concept:: Integrated Solutions for PVT (Hoppe, Olmann)

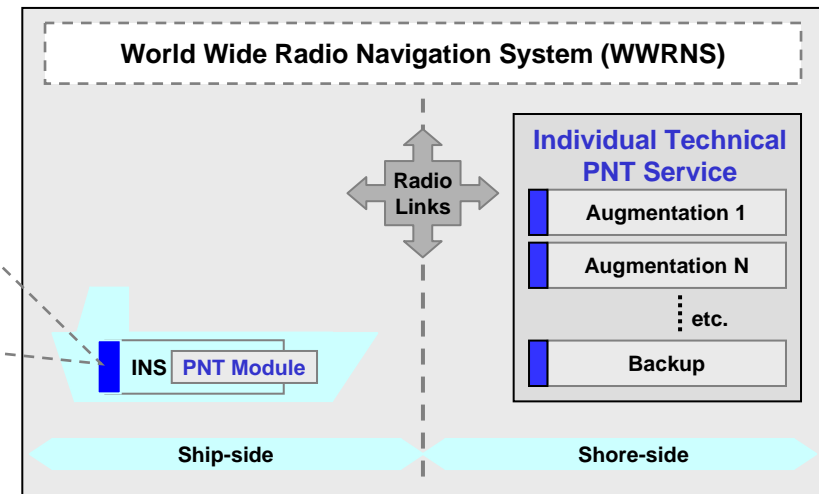
# Onboard PNT Module



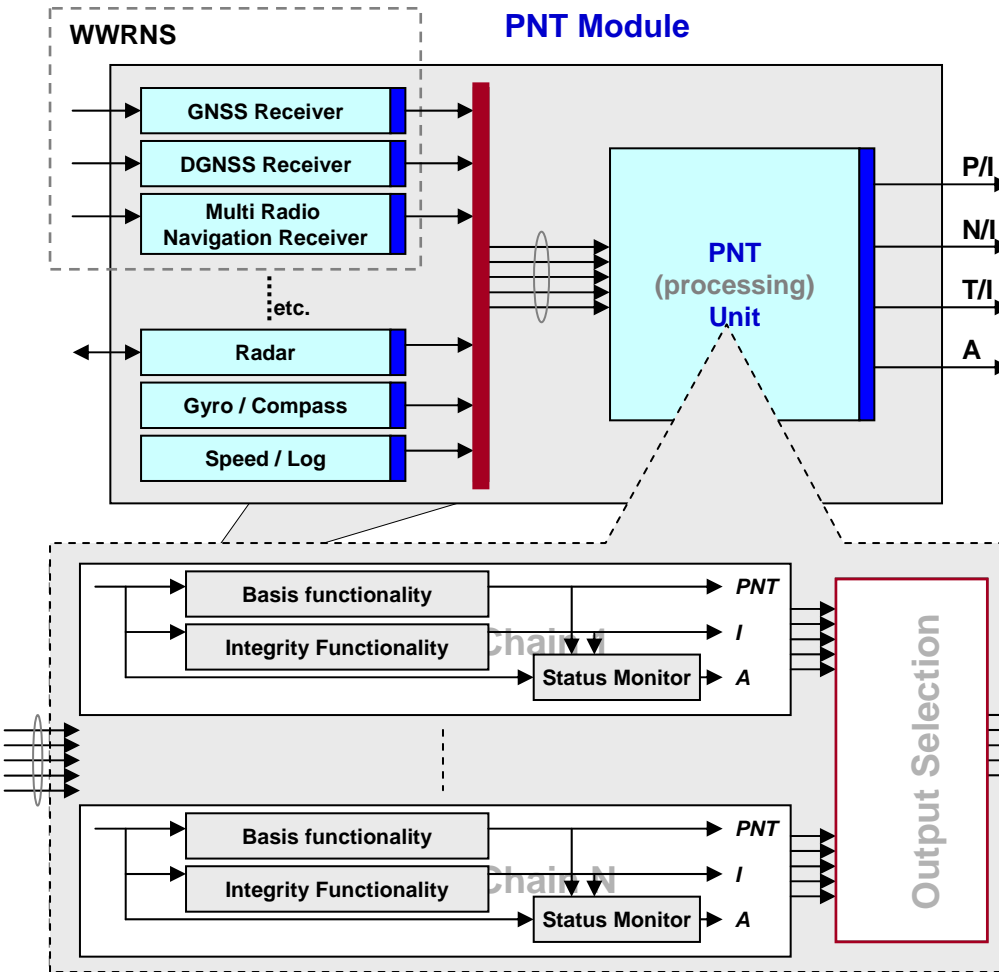
## Legend:

- - Product specification by Performance Standard
- P/I - Position and Integrity Data
- N/I - Navigation and Integrity Data
- T/I - Time and Integrity Data
- A - Alert Data

## Integrated PNT System



# Onboard PNT Module



- Creation of “true” redundancy by supported use of all PNT relevant sensor data including data of GNSS/DGNSS and future backup systems
- Introduction of parallel processing chains for robust PNT data provision under consideration of available augmentation and backup services
- Implementation of accuracy assessment (integrity functionality) per processing chain, if possible
- Performance controlled provision of “best” PNT output data
- Additional Provision of accuracy assessment results (integrity data)
- PNT relevant alert messaging for alarm management of Integrated Navigation System (INS) – paradigm shift



# Safety, Risk and Integrity

**Safety** = System state free of intolerable risks

$$\text{Risk} = P_{\text{Accident}} \cdot \text{Consequence(s)}$$



**Safety of Integrated PNT System**

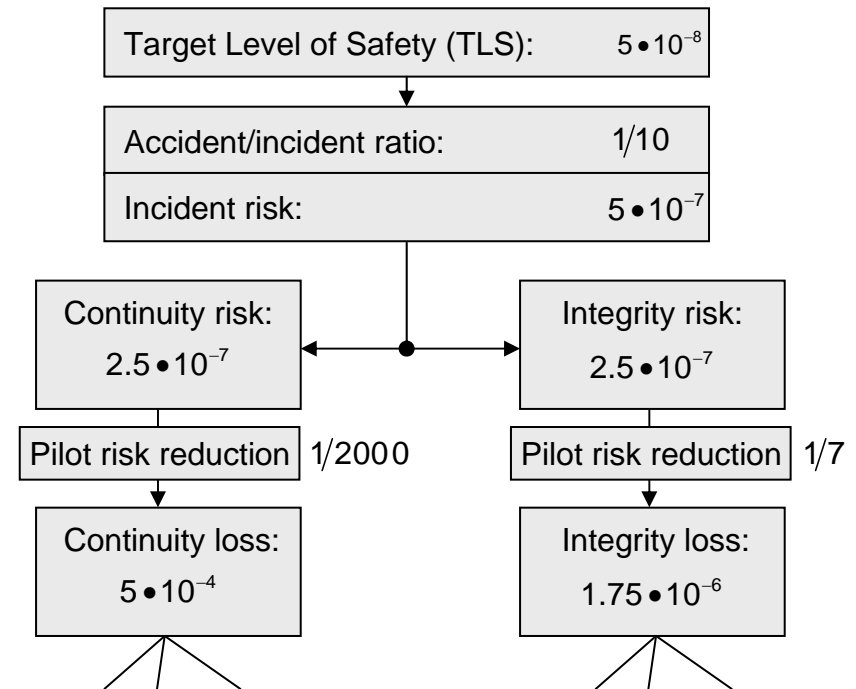
requires

**risk distribution** (fault tree analysis) & **management**

## Project MarNIS:

First fault tree for port approach:

- Max. 1 accident per year induced by GNSS is tolerable considering estimated number of global port approaches
- Accident/incident ratio: only accidents result into consequences.
- Equal risk distribution on continuity and integrity risk?
- Risk reduction by human factor – tbc.
- Result of tolerable loss of continuity and integrity.



# Conclusions (1)

- The integrated PNT system is an **identified core element** for safe ship navigation to avoid collision and grounding
  - by resilient ship-side situation awareness
  - by reliable vessel traffic management
- **Automatic assessment of accuracy and integrity** of PNT data is an identified user need. This requires
  - **completion** of performance requirements for all PNT data
  - **redundancy** introduced by sensors, services, and processing techniques
  - **integrated consideration** of applicable complete processing chains regarding their achievable performance (error mitigation and propagation)
  - introduction of **performance key identifiers** for integrity monitoring and alert generation per processing chain
  - **harmonised meaning** of provided integrity information
- **Automatic assessment of accuracy and integrity** of PNT data enables the selection of the best PNT data at consistent common reference points.

## Conclusions (2)

- **Detailed architecture design** of the Integrated PNT System is necessary
  - to describe the existing variety of **multi-sensor, multi-system and multi-service based processing chains** during berth to berth navigation
  - to assess the processing chains regarding the **accuracy of PNT data provision** and the **capability of integrity monitoring**
  - to enable **safety assessment analysis** and detailed identification of **technical gaps**
- The development of an **overall integrity concept** for the Integrated PNT System should be aimed
  - to improve **integrity monitoring** with **shared responsibilities** (ashore, aboard)
  - to enable scalability and **quantification of reliability**
  - to prepare an **operative risk management** inside the Integrated PNT System
- A paradigm shift from sensor related alert messages to output data related alert messages can support the **prioritisation and reduction of PNT relevant alarm messages**.